

LASER-BASED ACOUSTO-OPTIC UPLINK COMMUNICATIONS TECHNIQUE

TO ALL WHOM IT MAY CONCERN:

BE IT KNOWN THAT (1) FLETCHER A. BLACKMON and (2) LYNN T. ANTONELLI, citizens of the United States of America, employees of the United States Government, (3) LEE E. ESTES and (4) GILBERT FAIN, citizens of the United States of America, and residents of (1) Forestdale, County of Barnstable, Commonwealth of Massachusetts, (2) Cranston, County of Kent, State of Rhode Island, (3) Mattapoisett, County of Plymouth, Commonwealth of Massachusetts, and (4) Freetown, County of Bristol, Commonwealth of Massachusetts, have invented certain new and useful improvements entitled as set forth above of which the following is a specification.

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5 STATEMENT OF GOVERNMENT INTEREST

6 The invention described herein may be manufactured and used  
7 by or for the Government of the United States of America for  
8 governmental purposes without the payment of any royalties  
9 thereon or therefor.

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11 BACKGROUND OF THE INVENTION

12 (1) Field of the Invention

13 The present invention relates to a method and an apparatus  
14 for performing non-contact acousto-optic uplink communications.  
15 More specifically, the present invention relates to a method and  
16 an apparatus for enabling communication between a submerged  
17 platform and an in-air platform via the transmission and  
18 reception of acoustic and optical signals.

19 (2) Description of Related Prior Art

20 Traditionally, underwater acoustic telemetry involves all  
21 in-water hardware to establish an acoustic communication link.  
22 No known method of communications from a submerged platform to  
23 an in-air platform exists. Conventionally, submerged platforms  
24 such as submarines have to surface to transmit their data to an

1 in-air platform or remote site. This procedure can be time  
2 consuming and inefficient as compared to a non-contact  
3 communications scheme.

4 What is therefore needed is a technique for facilitating  
5 the communication of information from an underwater platform to  
6 an above-surface platform without establishing a physical link  
7 or line of communication between the two.

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#### 9 SUMMARY OF THE INVENTION

10 Accordingly, it is an object of the present invention to  
11 provide a method and apparatus for performing a non-contact  
12 acousto-optic uplink communication.

13 In accordance with the present invention, an apparatus for  
14 enabling acousto-optic communication comprises an in-water  
15 platform emitting an acoustic signal to an acousto-optic  
16 interaction zone. An in-air platform transmits a first  
17 interrogation laser beam, a portion of the first interrogation  
18 laser beam and a reflection of the first interrogation laser  
19 beam from the acousto-optic interaction zone. The in-air  
20 platform measures the differences between the received beams. A  
21 plurality of optical interferences between the portion of the  
22 first interrogation laser beam and the received second laser  
23 beam are provided as output. A signal converter receives the

1 plurality of optical interferences and provides an electrical  
2 signal representing the in-water acoustic communication signal.

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#### 4 BRIEF DESCRIPTION OF THE DRAWINGS

5 FIG. 1 provides a schematic diagram of the acousto-optic  
6 communication system of the present invention; and

7 FIG. 2 provides an illustration of the orientation and  
8 implementation of the in-air and in-water platforms of the  
9 present invention.

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#### 11 DESCRIPTION OF THE PREFERRED EMBODIMENT(S)

12 This invention provides a non-contact laser-based sensor  
13 acousto-optic communications uplink capability using the  
14 concepts of laser Doppler vibrometry, i.e., optical  
15 interrogation of the air-water interface, to detect velocity  
16 perturbations which provide information on the signal structure  
17 spectrum and time domain signal of the underwater acoustic  
18 waveform.

19 With reference to FIG. 1 there is illustrated the apparatus  
20 of the present invention. In-water platform 17 transmits an  
21 acoustic telemetry signal 19 to an acousto-optic interaction  
22 zone 21. In a preferred embodiment, in-water platform 17 is a  
23 platform such as a submarine fully submerged in a body of water.  
24 However, in-water platform 17 may be any platform submerged or

1 partially submerged in water including, but not limited to, sea  
2 vessels, submersibles and remote sensing platforms. In a  
3 preferred embodiment, the acoustic signal is comprised of a  
4 scheme for underwater propagation such as multi-frequency shift  
5 keying (MFSK), M-ary phase shift keying (M-PSK), or M-ary  
6 quadrature amplitude modulation (M-QAM). In a preferred  
7 embodiment, acoustic telemetry signal 19 is provided  
8 electrically by a processor 18 to an acoustic projector 20 which  
9 projects acoustic telemetry signal 19 into environmental water  
10 31.

11 Acoustic telemetry signal 19 is emitted from in-water  
12 platform 17 towards acousto-optic interaction zone 21. Acousto-  
13 optic interaction zone 21 is contiguous to air-water boundary  
14 27. In FIGS. 1 and 2, the air is indicated as 29 and the water  
15 as 31. As such, part of acousto-optic interaction zone 21  
16 consists of an area of the surface boundary between the air 29  
17 and the water 31. The interaction of the acoustic telemetry  
18 signal 19 with the acousto-optic interaction zone 21 causes  
19 physical perturbations in the air-water, pressure release  
20 boundary 27. These perturbations take the form of surface  
21 vibrations.

22 In-air platform 11 transmits an optical interrogation laser  
23 beam 25 created by a laser 32 towards the acousto-optic  
24 interaction zone 21 at a time when the perturbations in the air-

1 water boundary 27 formed at the acousto-optic interaction zone  
2 21 are expected. In a preferred embodiment, in-air platform 11  
3 is a rotary winged aircraft capable of hovering over and in  
4 proximity to acousto-optic interaction zone 21 as illustrated in  
5 FIG. 2. While described in relation to a helicopter, the  
6 present invention is not so limited. Rather, the in-air  
7 platform of the present invention is broadly drawn to include  
8 any platform located above the air-water boundary capable of  
9 emitting an interrogation beam 25 including, but not limited to,  
10 fixed wing aircraft, satellites, land based systems, and  
11 portions of a sea vessel located above water.

12 The interrogation beam 25 is reflected off the air-water  
13 boundary 27 and back to in-air platform 11 for reception as a  
14 received reflection beam 23. Although, in the preferred  
15 embodiment, interrogation beam 25 and reflection beam 23 are  
16 transmitted and received at the same platform, different  
17 platforms could be used for transmitting and receiving. Having  
18 been formed from a reflection off of a surface experiencing  
19 vibrational perturbations, received reflection beam 23 is laser  
20 light altered to include numerous frequency shifts corresponding  
21 to the vibrational perturbations of the acousto-optic  
22 interaction zone 21.

23 Analysis of the received reflection beam 23 may be  
24 performed to recover acoustic telemetry signal 19 using the

1 invention as claimed hereinafter. Laser Doppler vibrometry  
2 refers to optical interrogations of the pressure release  
3 interface and layers slightly below the surface to detect  
4 velocity perturbations. A laser doppler vibrometer 36 is joined  
5 to single sensor or a number of sensors 34 arranged to obtain  
6 beam formable array data. A splitter 38 is used to divide out  
7 unperturbed portion of the interrogation beam 25' from the  
8 interrogation beam 25. The unperturbed beam portion 25' is used  
9 as a reference to compare with received reflected beam 23. As  
10 noted above, received reflection beam 23 is perturbed by the  
11 vibrations in the air-water boundary 27 in contact with acousto-  
12 optic interaction zone 21. The optical interference between the  
13 two beams 23, 25 are measured as a Doppler velocity by an  
14 interference vibrometer 36, which is then converted to an  
15 electrical representation of the acoustic signal in the form of  
16 an electrical signal by acoustic/photonic/electrical signal  
17 converter 13. Acoustic/photonic/electrical signal converter 13  
18 outputs the electrical signal to a telemetry receiver 15.  
19 Telemetry receiver demodulates or otherwise decodes the  
20 electrical signal to recreate the received acoustic telemetry  
21 signal at the air-water interface.

22 Because the perturbations to the acousto-optic interaction  
23 zone 21 occur over a finite time and space, advance knowledge of  
24 the time and place to emit and receive optical interrogation

1 beams is generally required by the in-air platform 11. This  
2 required knowledge adds a layer of data transmission security,  
3 preventing unwanted parties from accessing the acoustic  
4 telemetry signals 19. In addition, the sensing capability of  
5 the present invention can be used for a number of related  
6 applications such as threat/marine mammal detection.

7       It is apparent that there has been provided in accordance  
8 with the present invention an apparatus for performing a non-  
9 contact acousto-optic uplink communications which fully  
10 satisfies the objects, means, and advantages set forth  
11 previously herein. While the present invention has been  
12 described in the context of specific embodiments thereof, other  
13 alternatives, modifications, and variations will become apparent  
14 to those skilled in the art having read the foregoing  
15 description. Accordingly, it is intended to embrace those  
16 alternatives, modifications, and variations as fall within the  
17 broad scope of the appended claims.